Shamak Dutta

Work Experience

2024 - now **Postdoctoral Scholar**, *University of Waterloo*, Canada.

Advisors: Yash Pant & Stephen L. Smith

- Building algorithms for large scale flight planning, GPU-accelerated heuristics for integer programming, and active machine learning in robotics.
- Collaborating with engineers and product managers at Airbus as part of a two year research project on flight planning and control.
- Mentoring graduate students on multiple research projects by providing technical guidance, sharing knowledge, and reviewing code.
 Keywords: PyTorch, Gurobi, Active machine learning, Linear programming, Integer programming.

Education

2024 PhD in Electrical and Computer Engineering, University of Waterloo, Canada.

Research: Robotics, Control, Machine Learning, Optimization

Advisor: Stephen L. Smith

Faculty of Engineering Award, Electrical and Computer Engineering (\$1.5k) (2023)

Graduate Research Dissemination Award, Faculty of Engineering (2023)

University of Waterloo Graduate Scholarship (\$1.2k) (2022) Teaching Assistant Award, Faculty of Engineering (2021)

GPA: 3.9/4.0

Thesis: Resource Constrained Linear Estimation in Sensor Scheduling & Informative Path Planning

2019 Masters in Systems Design Engineering, University of Waterloo, Canada.

Research: Machine Learning, Computational Neuroscience

Advisors: Bryan Tripp & Graham Taylor

Vector Institute Research Award (\$4k) (2018, 2019)

University of Waterloo Graduate Scholarship (\$1k) (2019)

International Master's Student Award (\$6.5k) (2018, 2019)

Thesis: Correlated Noise in Deep Convolutional Neural Networks

2017 **Bachelors in Computer Engineering**, *University of Waterloo*, Canada.

Engineering International Student Scholarship (\$20k) (2013)

President's Scholarship of Distinction (\$2k) (2013) President's Research Award (\$1.5k) (2015)

GPA: 3.7/4.0 (Distinction)

Selected Publications

My research focuses on data-efficient learning subject to constraints on time, energy, and network communication. I develop optimal, approximation, and heuristic algorithms for problems in robot information acquisition.

2025 Informative Path Planning for Active Regression with Gaussian Processes via Sparse Optimization.

S. Dutta, N. Wilde, S. L. Smith

IEEE Transactions on Robotics (T-RO), 2025.

- o Provides the first algorithm to compute optimal solutions for active learning and planning in GPs with sampling and routing constraints.
- Keywords: Active learning, Integer programming, Gaussian Processes, Gurobi.

2023 A Unified Approach to Optimally Solving Sensor Scheduling and Selection Problems in Kalman Filtering.

S. Dutta, N. Wilde, S. L. Smith

IEEE Conference on Decision and Control (CDC), 2023.

- o Developed an algorithm that computes optimal solutions for active learning in the estimation of linear dynamical systems.
- Keywords: Kalman filtering, Integer programming, Gurobi.

2023 Approximation Algorithms for Robot Tours in Random Fields with Guaranteed Estimation Accuracy.

S. Dutta, N. Wilde, P. Tokekar, S. L. Smith

IEEE International Conference on Robotics and Automation (ICRA), 2023

- o Developed an algorithm achieving $6 \times$ data efficiency and $2 \times$ shorter tours compared to existing approaches for active learning in GPs.
- Keywords: Set covering and packing, Traveling salesman problems, Approximation algorithms, Gaussian Processes.

2022 An Improved Greedy Algorithm for Subset Selection in Linear Estimation.

S. Dutta, N. Wilde, S. L. Smith

IEEE European Control Conference (ECC), 2022.

- \circ Designed an algorithm achieving 2 imes improvement in runtime and solution quality for finding the best k-measurement subset to learn a spatial field.
- Keywords: Clique covering, Greedy, Gaussian Processes.

Selected Internships

2018 Research Intern, Preferred Networks, Tokyo, Japan.

Advisors: Shunta Saito & Masaki Saito

2017 Research Intern, Latent Logic (now Waymo), Oxford, United Kingdom.

Advisors: Joao Messias & Shimon Whiteson

2016 Research Intern, Amazon Search, Palo Alto, USA.

Advisors: Bing Yin & Erick Cantu-Paz